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# Minis-Robot Software ENTRANCE GUIDE

MiniStudio Inc. Jan. 12, 2008



#### **MIniS-Robot's feature**



(1)Easy to start, for robotics learning step by step.

(2)Various robots stem from your limitless imagination.

(3)Experience the enjoyment while making human robot at low price













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## **Hint of Assembly**

make double Axis Servo

Notice the assembly

sequence





distinguish various type of the screw.





Let number of the channel correspond to the servo position according to the software.





#### **How to Start Motion**

- (1) Start Controller program
- (2) Check on the synch
- (3)Make initial and guard data
- (4) Use Relative function
- (5) Adjustment of Pose
- (6) Capture the Pose
- (7) Save the motion CSV data
- (8) Read CSV File
- (9) Run the Motion
- (10) Write data to PIC Chip



### (1) Start Controller program

(1) Confirm program in the Directory c:¥MiniStudio

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(2) It's convenient to make a shortcut in Desktop

(3) Link the serial port, if no COM port on PC Use Z-TEK USBto232 converter

(4) Confirm the port number you are using



MiniSCon.



### (2) Check on the synch



Synch can make servo work simultaneously corresponding to software Slider, spin box or Edit box setting.



#### (3)Make initial and guard data

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MiniStudio Inc., copyright 2005-20 不同的机器人初始位置可能略有不同。 采用相对位置数据表示方式便于数据表	38				Note:do not use "relative" at this time

You should make a initial (home) data after you assembly your robot. Please set home, max, and min data and connect servo one by one.



#### (4) Use Relative function



It is convenient to use this function to input data, at this state you may find the data is symmetric.

#### (5) Adjustment of Pose



Click the picture you may find Servo position and use software Slider, spin box or Edit box setting to adjust servo angle.



## (6) Capture the Pose



Make sure the Speed Step and use Capture button to freeze the data.

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### (7) Save the motion CSV data

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A set of pose data constitute the motion. Use save button to record to PC hard disk



## (8) Read CSV File

Use open button to read the data from PC



### (9) Run the Motion

TiniS-Controller Ver.1.0		
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Use play button to run the motion, you may edit the CSV file by using MS Excel.

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#### (10) Write data to PIC Chip



Without PC you may also let Robot show your data

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# Thank you for your using Minis-Robot!

